

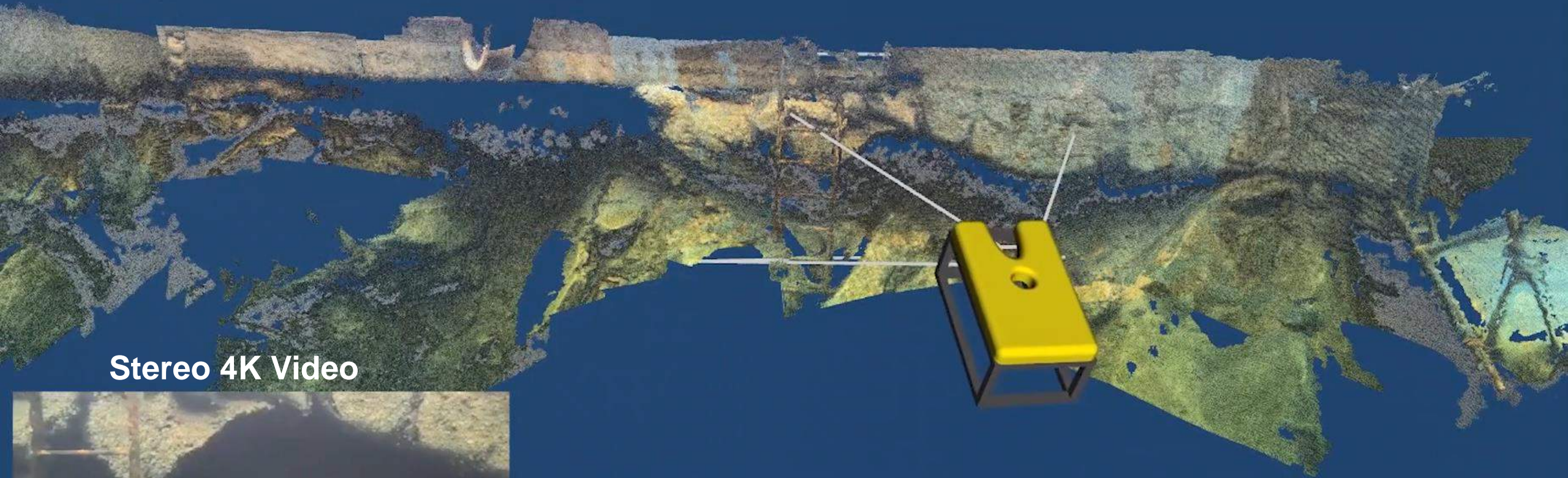


# A Technical Road Map to Our Autonomous Future

Joe Tidball, Survey Manager  
[joe.tidball@rovco.com](mailto:joe.tidball@rovco.com)



# Future - Live 3D Computer Vision

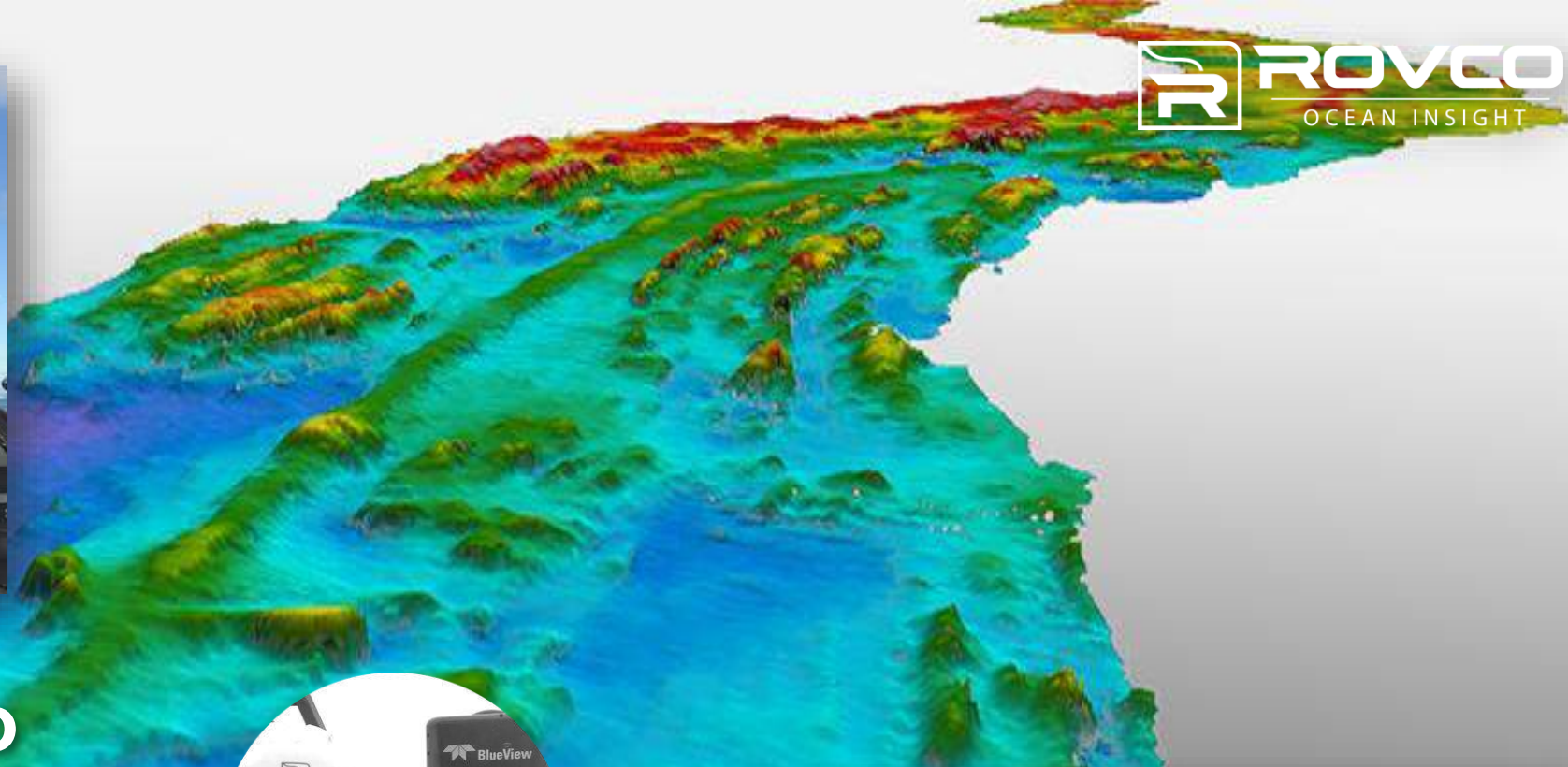


Stereo 4K Video



To view video, [click here.](#)





# Introducing Rovco

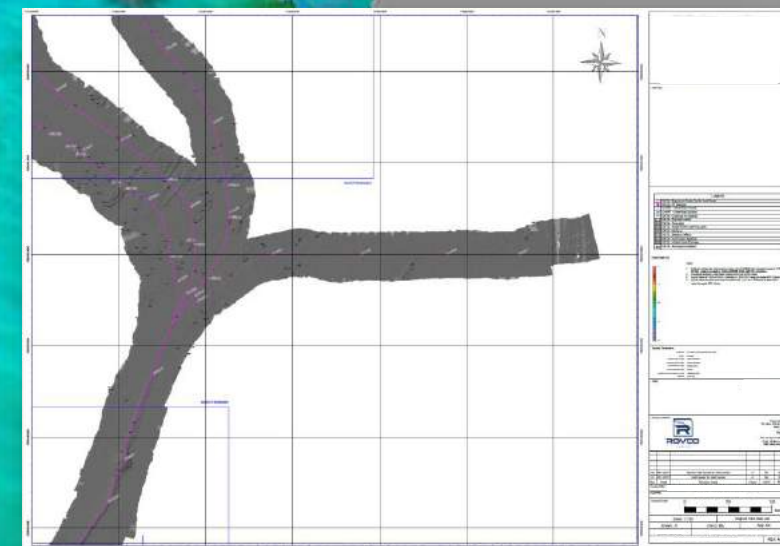
22 Staff based in Bristol, UK

5 ROVs – Survey Class

Hydrographic Survey & ROV



**Joe Tidball**  
Survey Manager  
MSc Hydrography  
Cat A Hydrographic Surveyor







3 month project, in S. America. ROV, USBL, habitat mapping with 3D





**3 year framework agreement, Gwynt Y Mor windfarm, ROV, cable survey, 3D**







Initial Decommissioning Survey. low cost spot market DP 2 Vessel, low cost spread

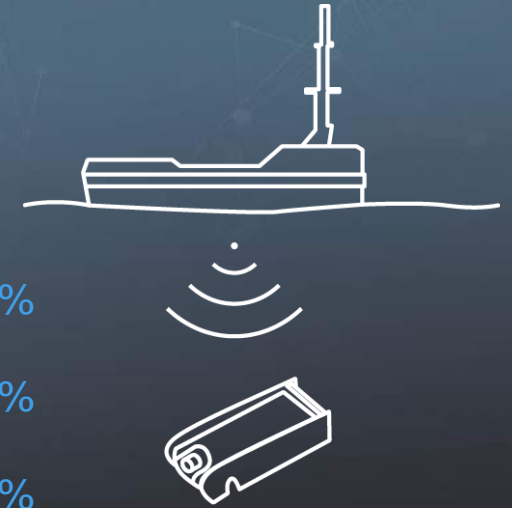


# Reduced cost of survey

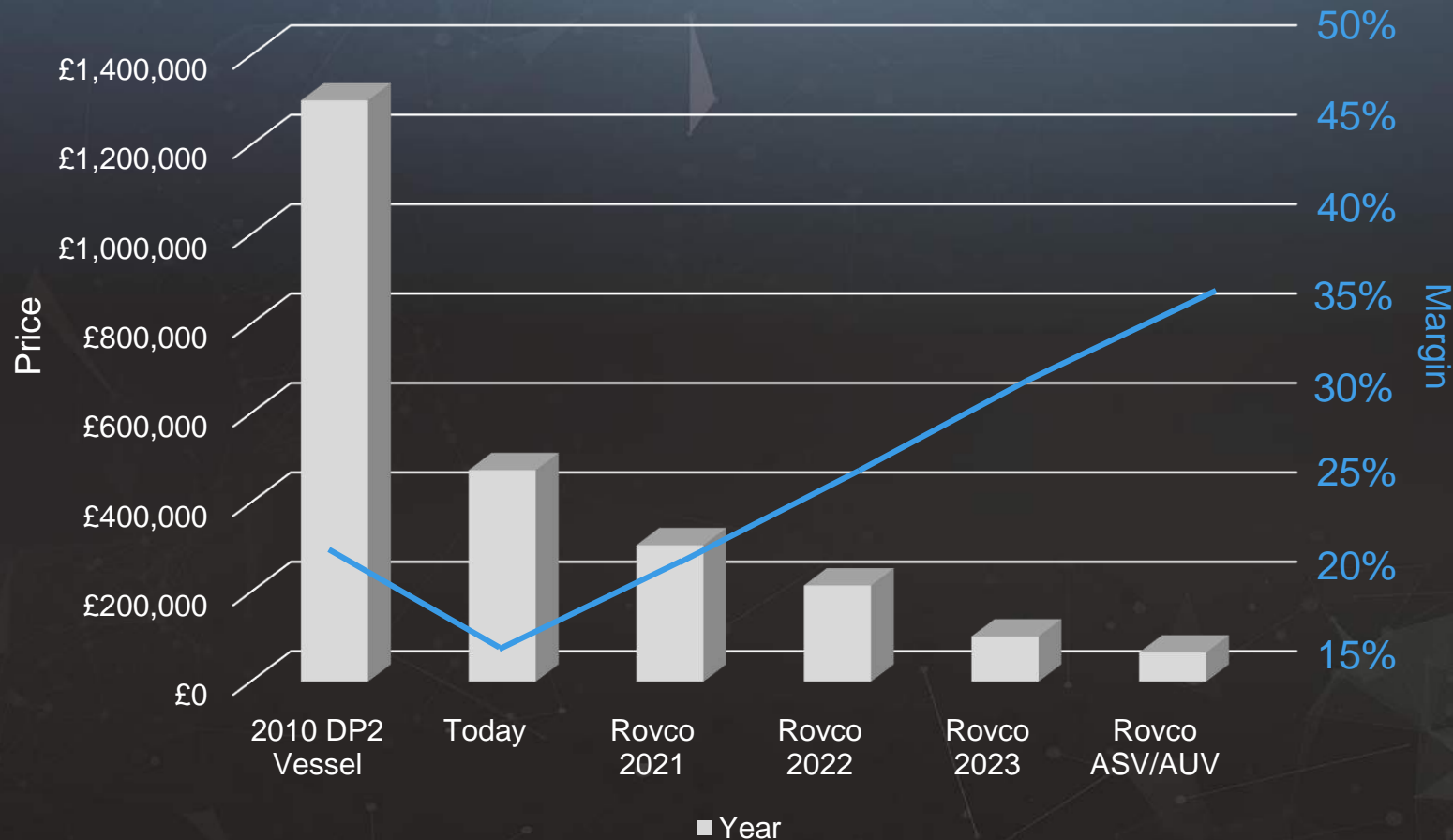


£6500/km

## Example 200km Pipe or Cable Survey



£330/km







# SubSLAM X1 Smart Camera

The building block in our autonomous future

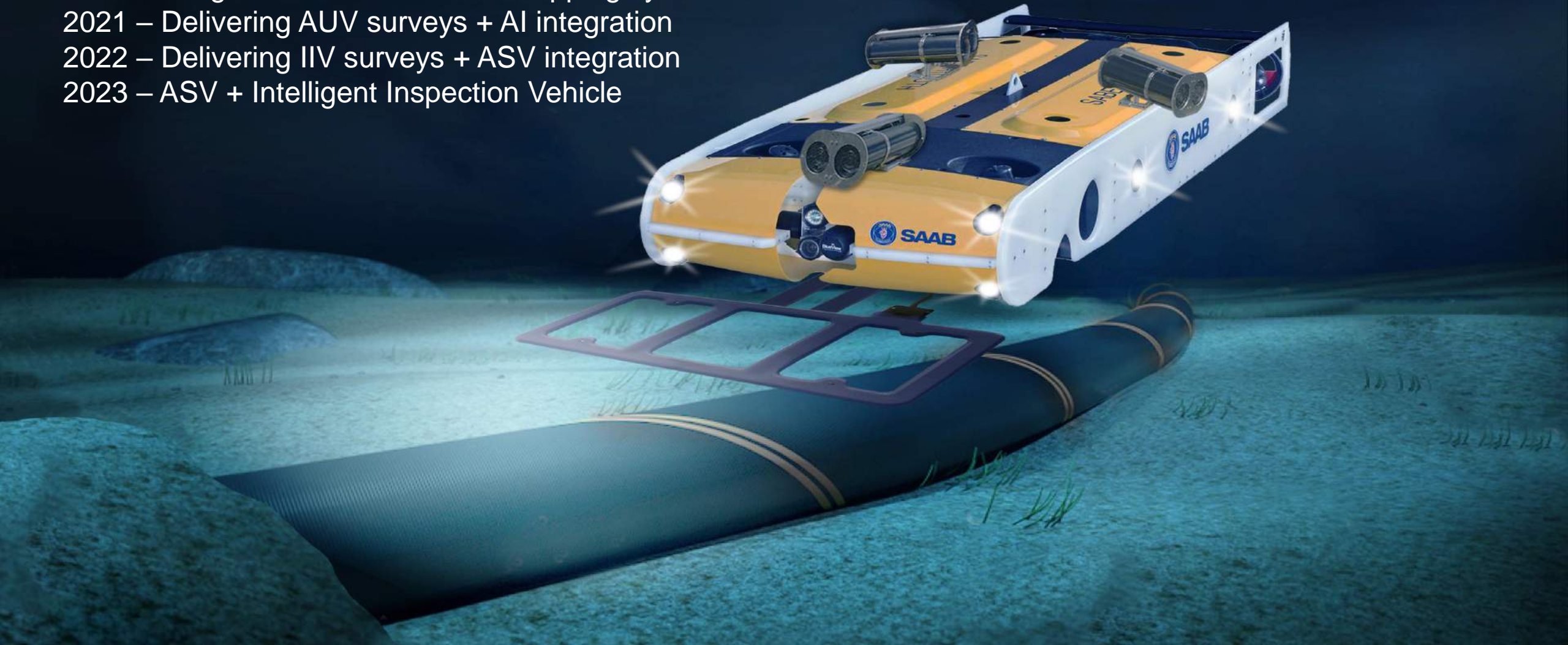
Patent Pending EP Patent Application Number 18192388.9 UK Patent Application Number 1814314.9





# Intelligent Inspection Vehicle

- 2019 – Rovco purchasing first AUV (Oct 19)
- 2020 – Integration with SubSLAM mapping system
- 2021 – Delivering AUV surveys + AI integration
- 2022 – Delivering IIV surveys + ASV integration
- 2023 – ASV + Intelligent Inspection Vehicle





# Live 3D Computer Vision



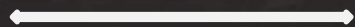
Live 3D Transmission



Autonomous Survey



Subsea Metrology



X=15.15m

Replacement  
USBL / LBL



Artificial Intelligence



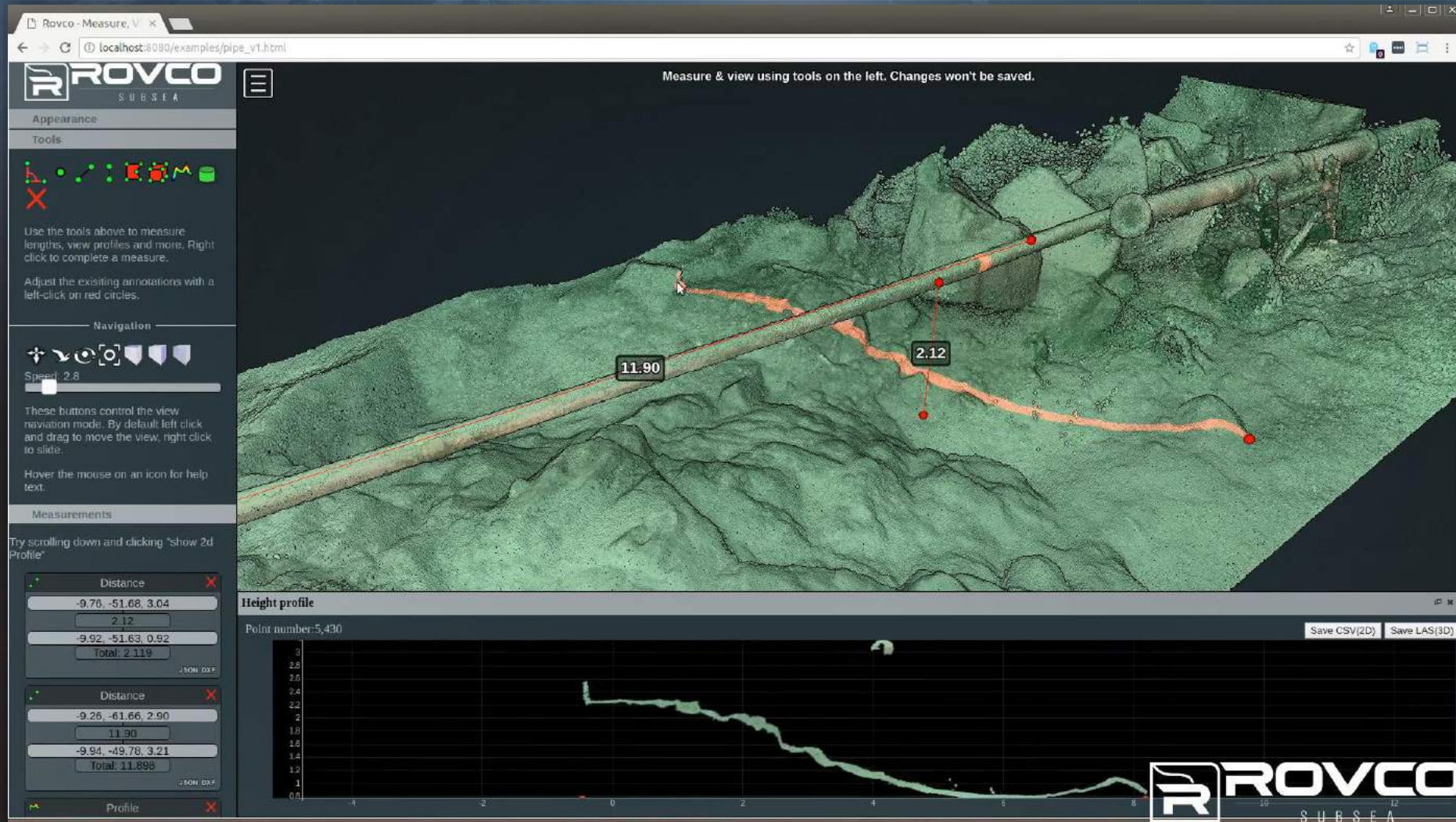


# Live 3D Transmission





# Live 3D Metrics



ROVCO Measure, V x

localhost:8080/examples/pipe\_v1.html

Measure & view using tools on the left. Changes won't be saved.

ROVCO SUBSEA

Appearance

Tools

Use the tools above to measure lengths, view profiles and more. Right click to complete a measure.

Adjust the existing annotations with a left-click on red circles.

Navigation

Speed: 2.8

These buttons control the view navigation mode. By default left click and drag to move the view, right click to slide.

Hover the mouse on an icon for help text.

Measurements

Try scrolling down and clicking "show 2d Profile"

Distance
-9.76, -51.68, 3.04
2.12
-9.92, -51.63, 0.92
Total: 2.119

JSON DXF

Distance
-9.26, -61.66, 2.90
11.90
-9.94, -49.78, 3.21
Total: 11.898

JSON DXF

Profile

Height profile

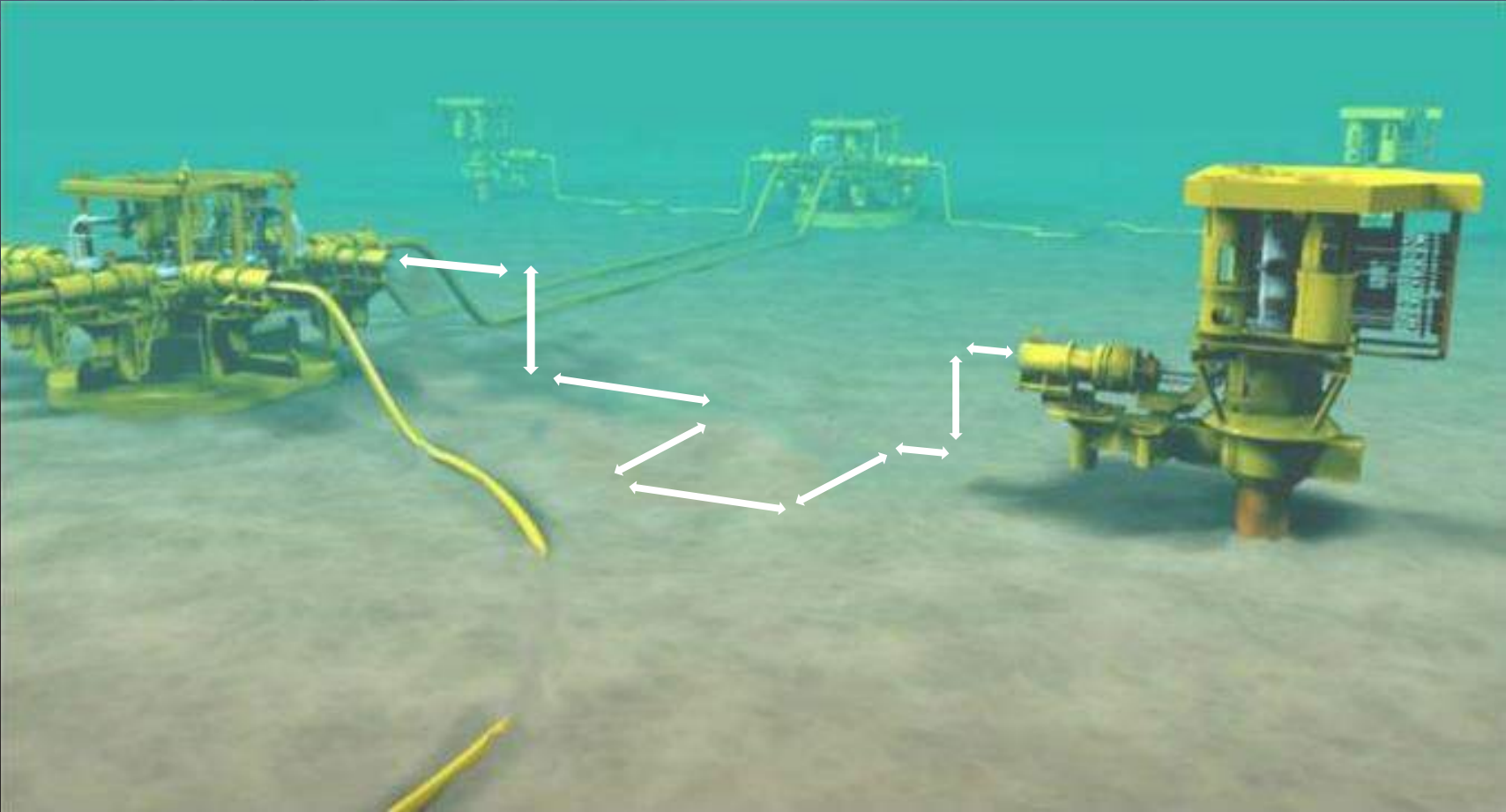
Point number: 5,430

Save CSV(2D) Save LAS(3D)

ROVCO SUBSEA

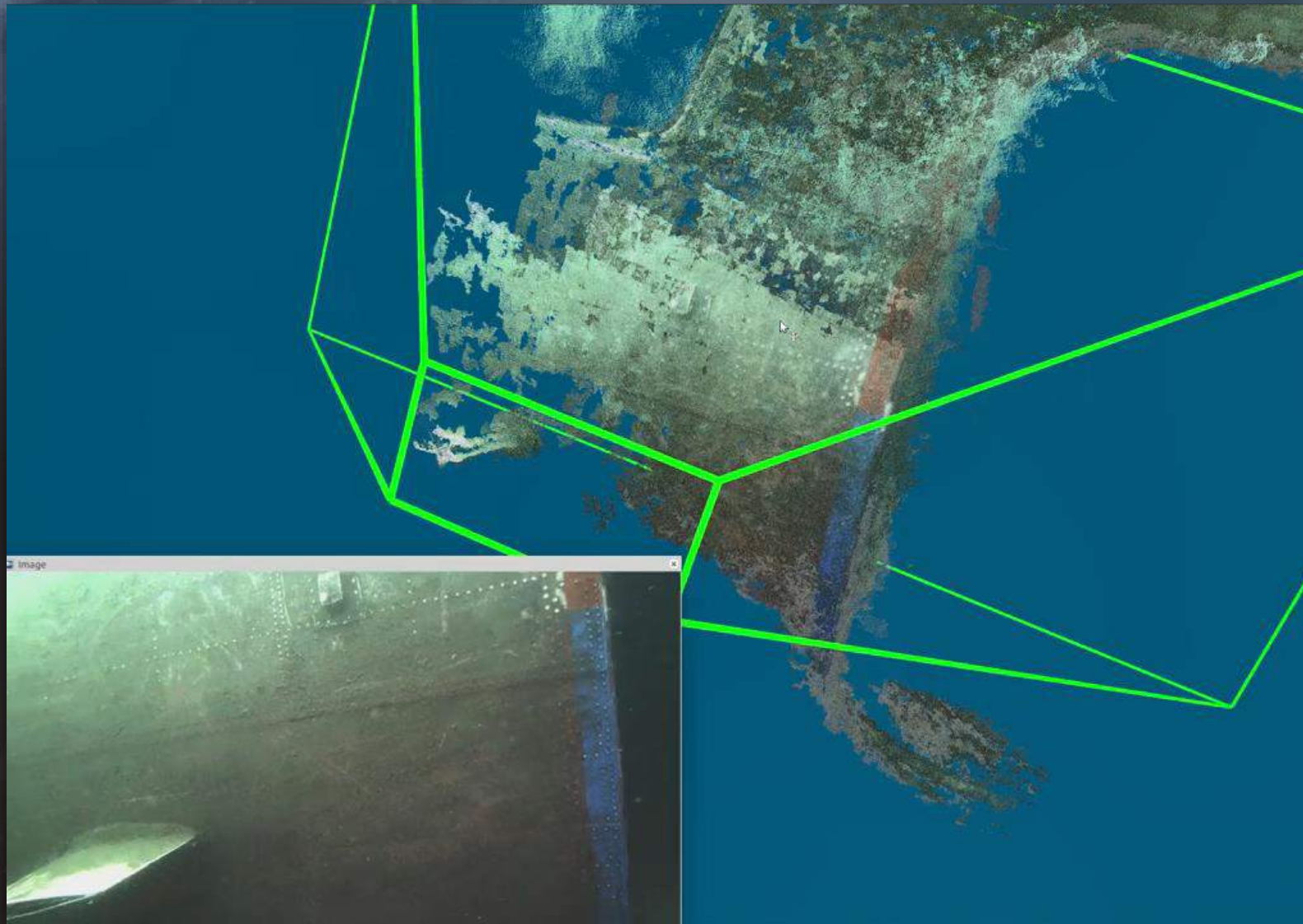


# Subsea Metrology





# mm perfect live survey



To view video, [click here.](#)





# Positioning Without Surveyors

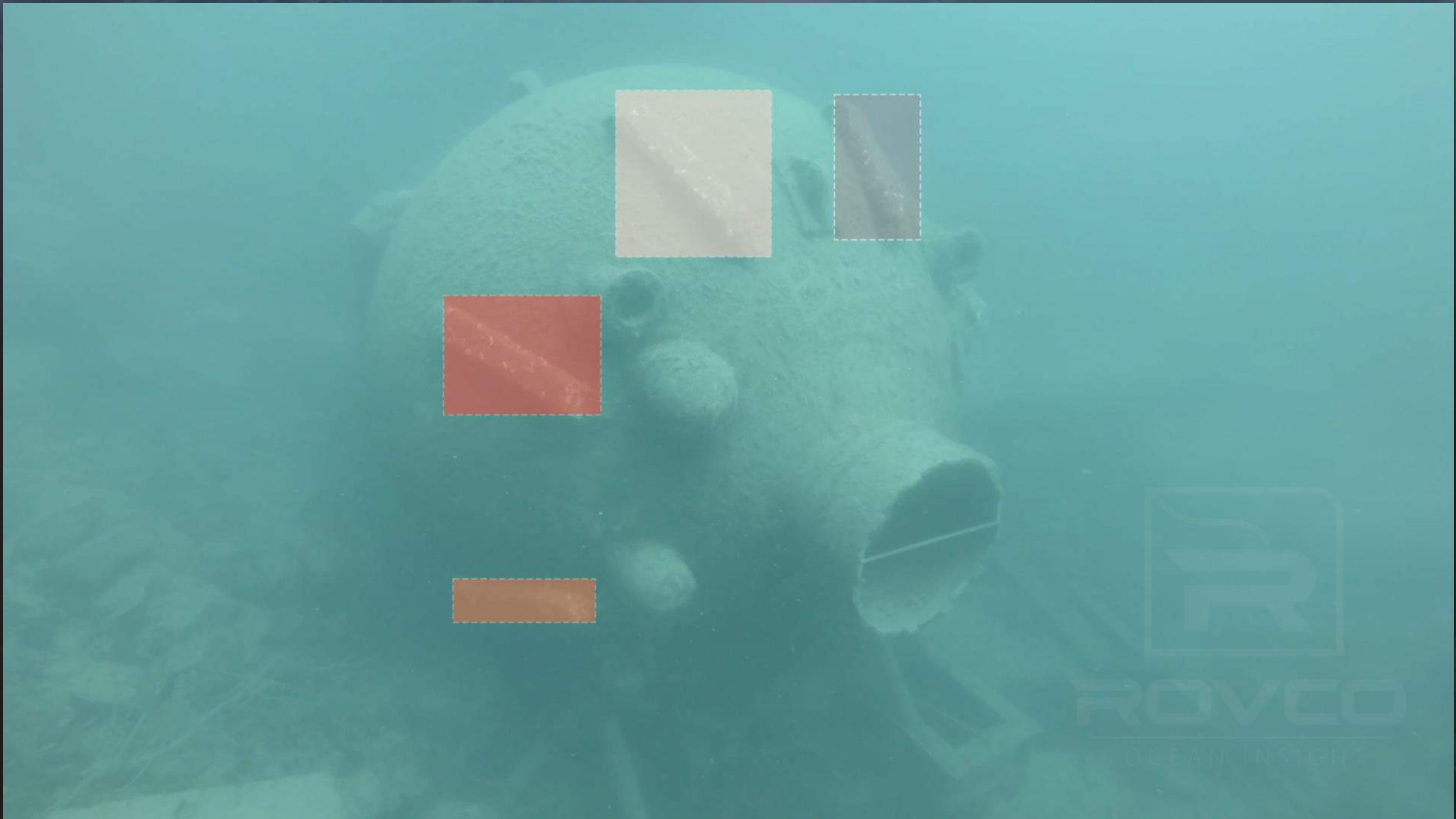


# SubSLAM replacing LBL and some USBL



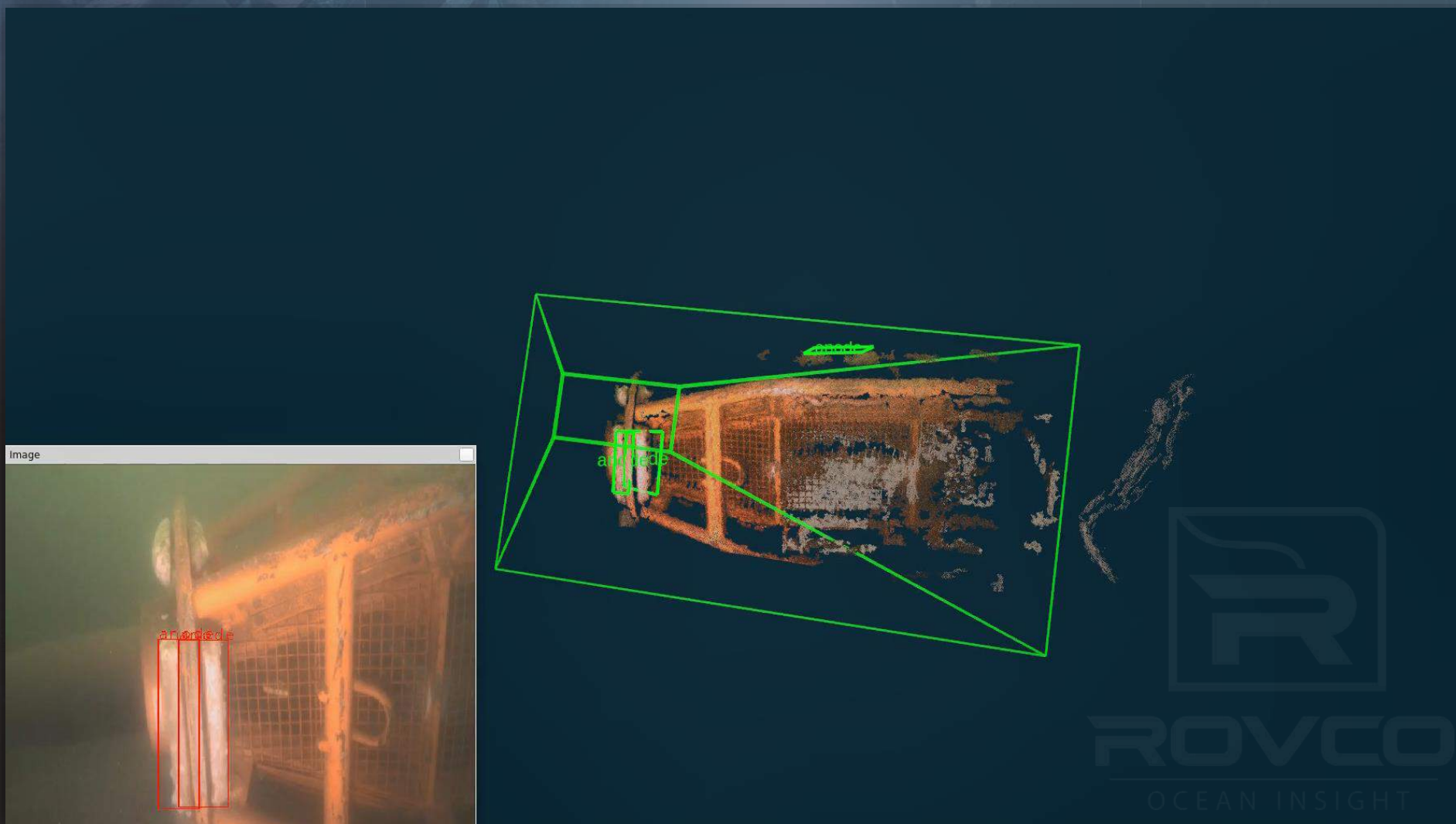


# Machine Learning



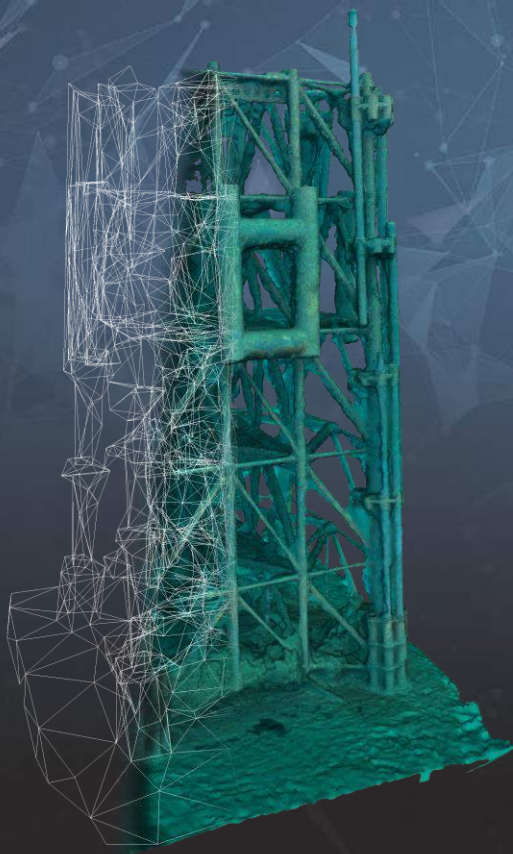


# Artificial Intelligence



To view video, [click here](#).





**World leaders  
3D Photogrammetry**



# 3D Photogrammetry

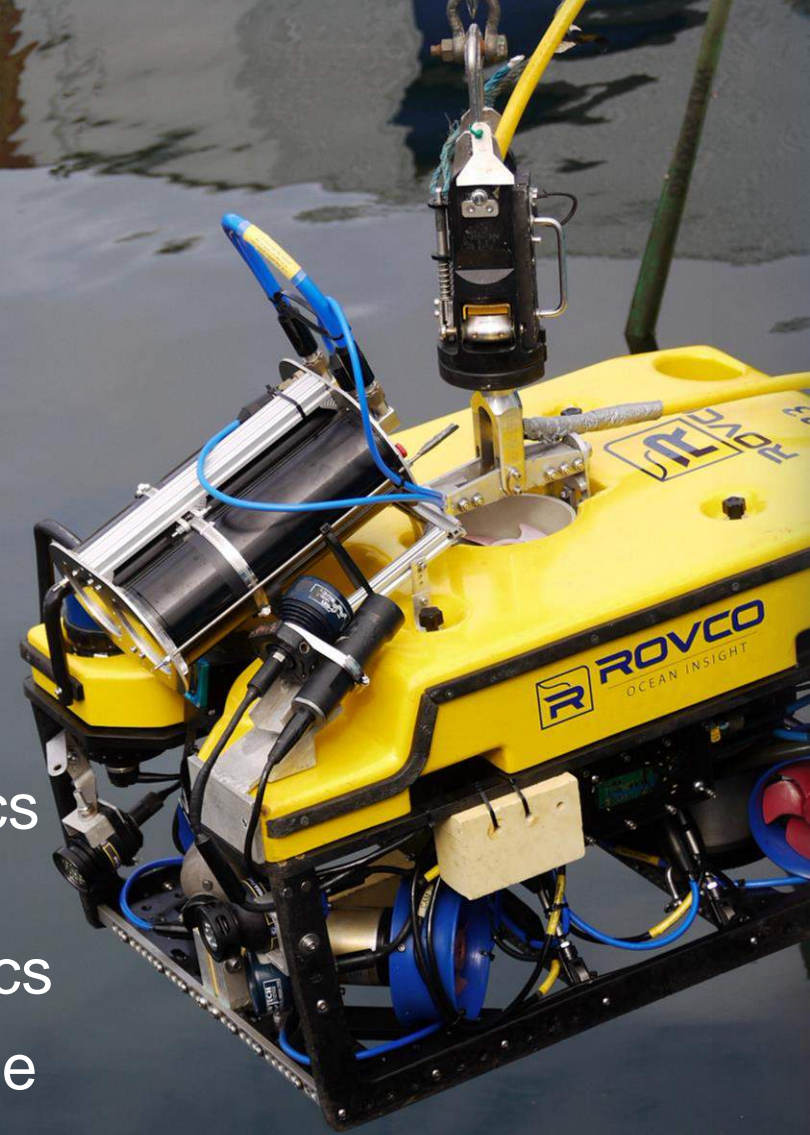




# Other Uses?

Smarter robots lead to smaller vessels and fewer people doing more, higher quality work.

- Accurate measurement
- Comparison
- Easy overviews
- Better data delivery
- Pretty pictures
- Repeatable, reliable metrics – measures of risk
- New, more complete metrics
- Higher quality, more reliable assessments of asset condition



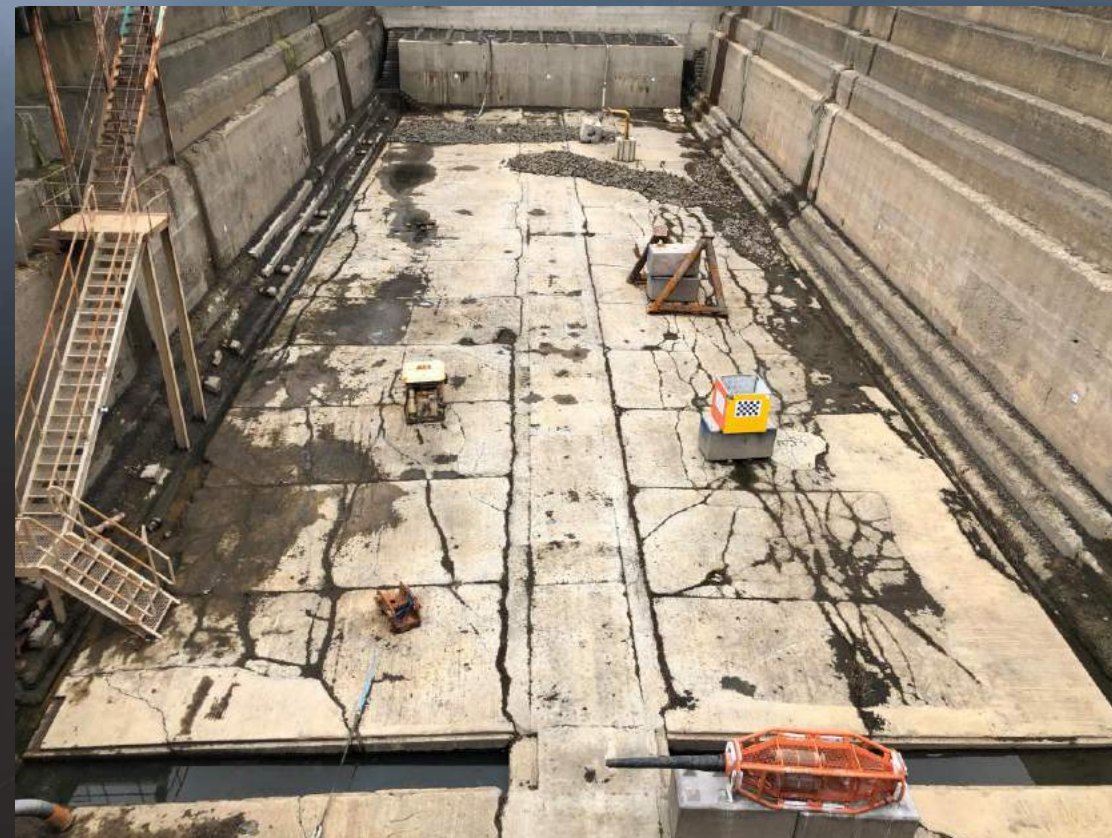




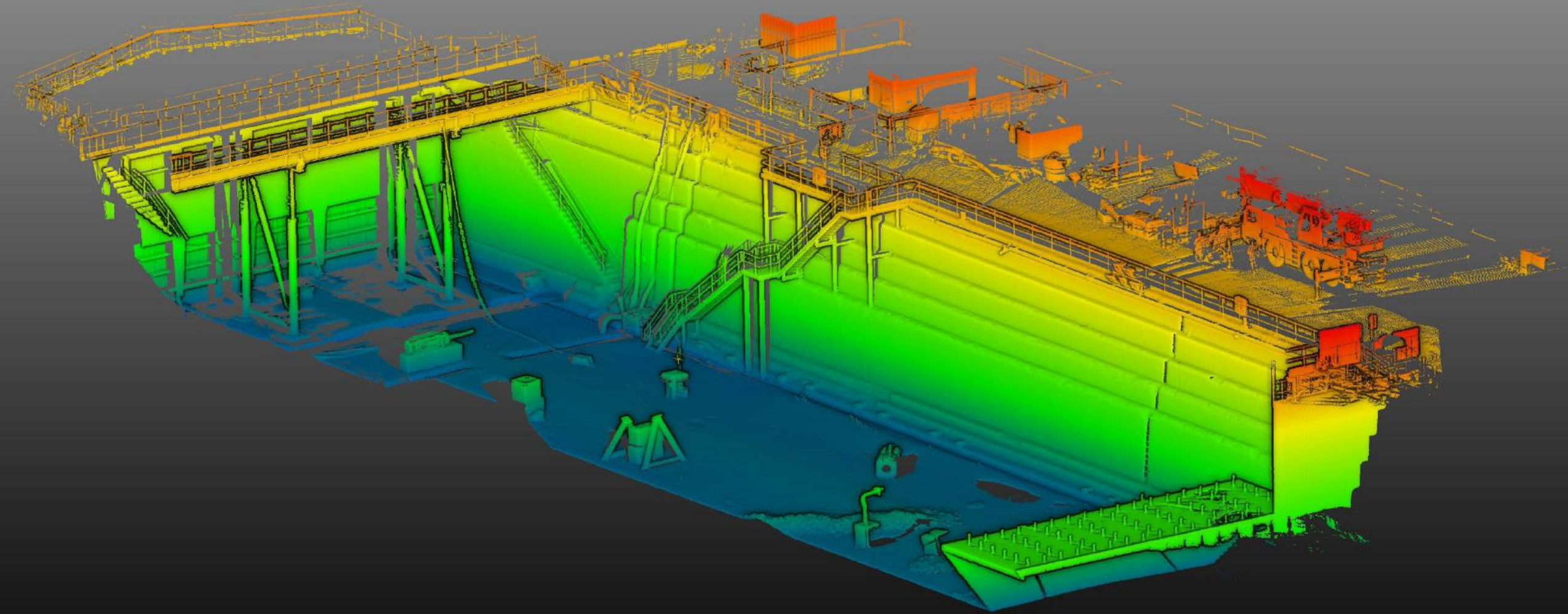
# System Accuracy & Testing



# Obtaining a Ground Truth







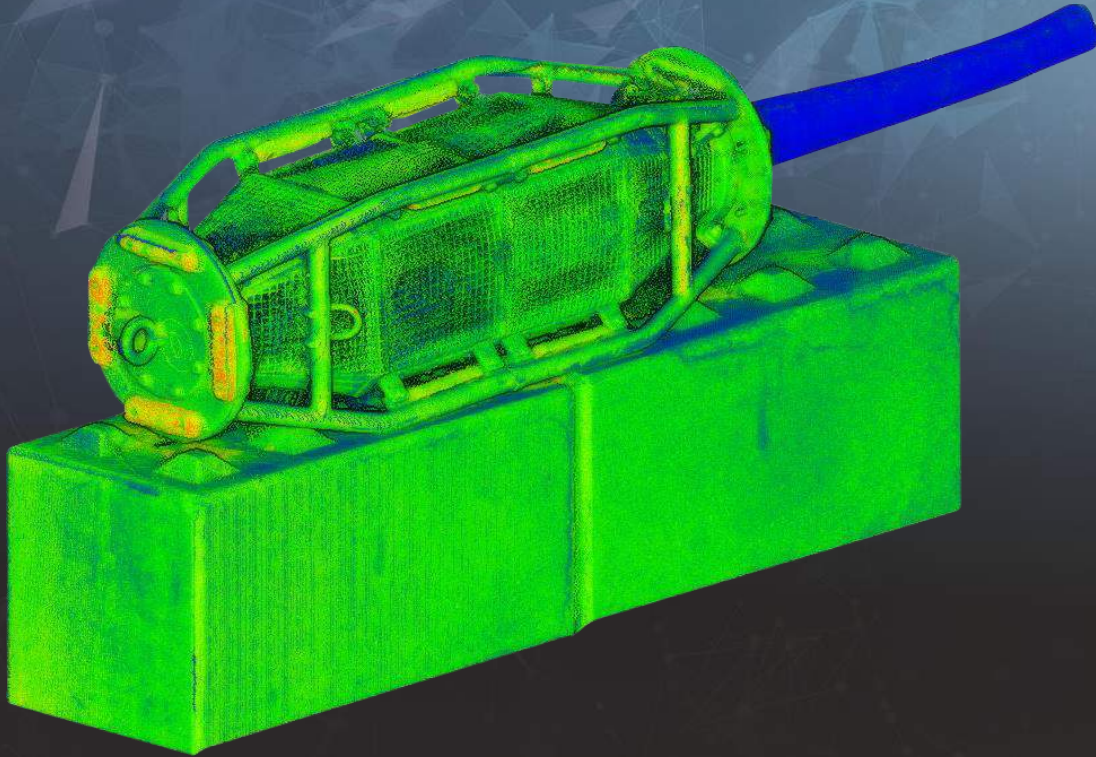


**1.2m**  
VISIBILITY





# Accurate Results



Leica P40    System Error            +- 2.3mm  
                 Alignment Error        +- 1.7mm  
                 Total Noise (1 $\sigma$ )       +- 4.0mm

Scan time 2hrs, stationary multiple scans, in air/good vis

SubSLAM    Point to Point Accuracy   +- 0.07%  
                 Error over 1m                +- 0.67mm  
                 Total Noise (1 $\sigma$ )        +- 4.0mm

Scan time 2mins, mobile ROV, 1.2m vis

SubSLAM photogrammetry comparison to Laser Scan – Equivalent Accuracy, Better Performance



# Rovco SubSLAM

Live 3D & Artificial Intelligence  
for ROVs and AUVs

Joe Tidball, Survey Manager  
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# Questions?

- What survey work can we deploy on today?
- What do you need to measure but can't?
- How do offshore roles change with automated technology?
- Is positioning without USBL/Surveyors interesting?
- Could live transmission of 3D back to HQ be useful?