# Xblue





# DTIX The mapping tool of the future

An ocean of possibilities

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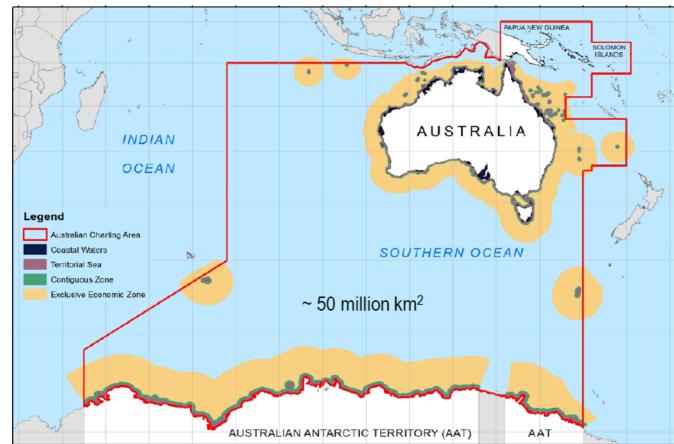
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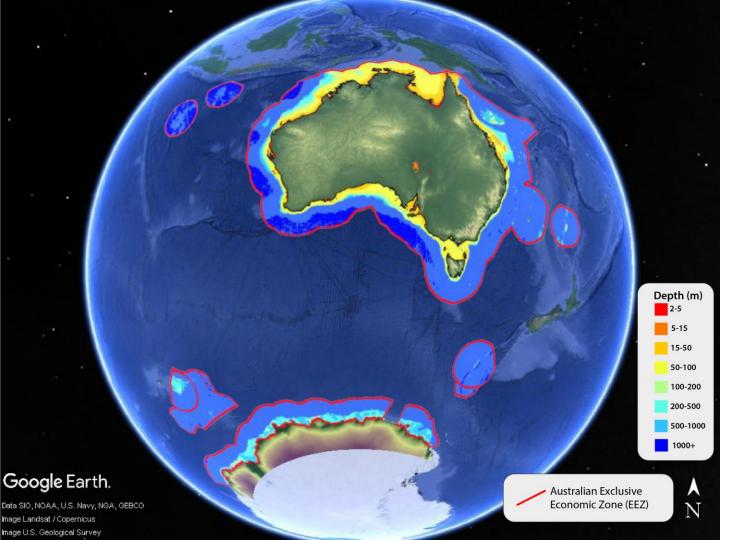
Australia's seafloor mapping problem
About DriX
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Cost benefits of DriX



# Australia's area of charting responsibility





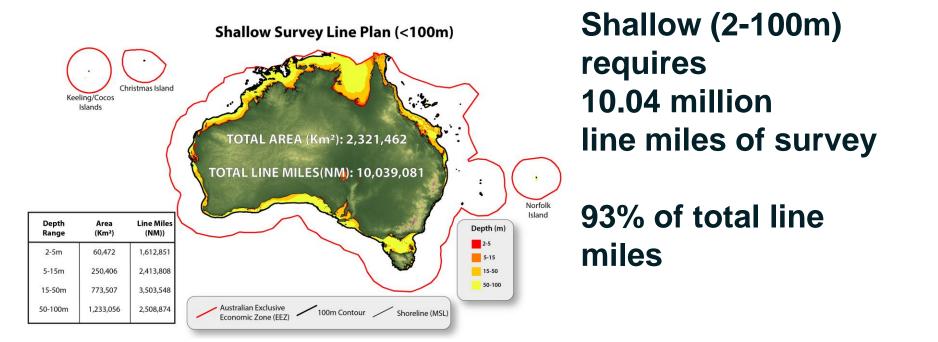


#### Australia's EEZ

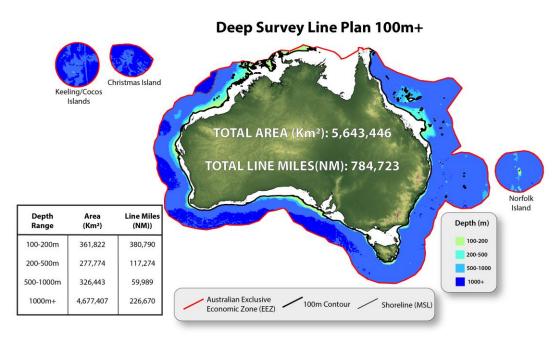
#### Mainland 9.3m km<sup>2</sup>

Antarctica 4.8m km<sup>2</sup>

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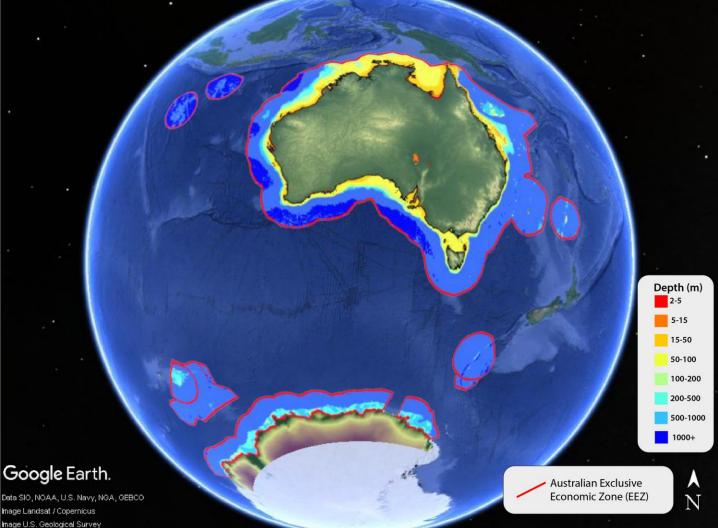






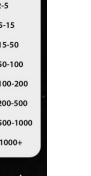
Deep (>100m) requires 785,000 line miles of survey

7% of total line miles even though it equates to 75% of EEZ by area



#### How long will it take to survey Australia's EEZ?

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#### Survey task too long and too expensive

How does industry increase output and reduce cost?

- Major cost drivers for survey work:
  - Expertise/Personnel
  - Equipment
  - Vessels
  - Risk Weather, sea-state, unknown bathymetric complexity
- Automating the vessel (and everything onboard) provides the biggest cost-saving

#### **Conclusion:**

• Using multiple autonomous vessels from a single host vessel offers significant efficiencies if allowed to operate for long periods of time





#### **Evolution of iXblue's USV interest**

Tried several USVs but remained unsatisfied

- Some were "good" but none were "perfect" for offshore use. All had some combination of:
  - Insufficient speed
  - Insufficient endurance
  - Poor sea-keeping
  - Bad acoustic sensor conditions
  - Insufficient payload
- iXblue had a shipyard, mechatronics and automation engineers, inertial navigation and acoustic systems engineers and surveyors **So we created our own USV... DriX.**

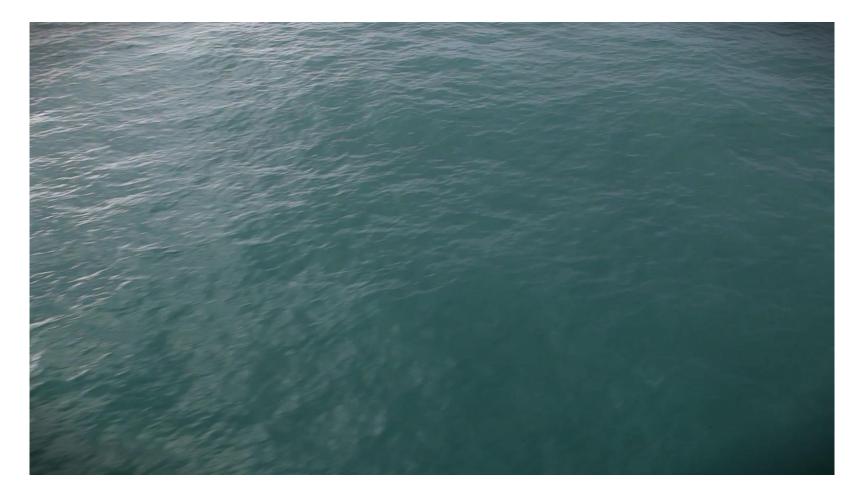




### **About DriX**



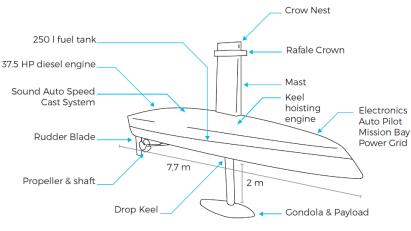


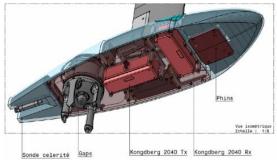




#### **Designed for offshore survey**

High speed, high endurance and versatile payload support





Speed: 14+ knots

#### **Endurance:**

14 days @ 4 knots 5 days @ 8 knots 2 days @ 14 knots

#### Sea keeping:

Operational - Sea state 5 Survival – unknown, unable to test (likely exceeds mothership capability)

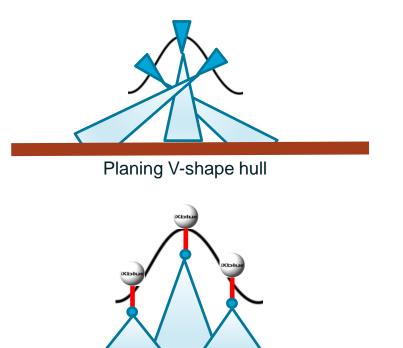
**Payload:** INS, USBL, MBES, GNSS, SVP, Radio broadband/UHF/Wifi/Satcom

**Navigation/Safety:** Panoramic visible/IR cameras, Al object recognition, adaptive path planning, AIS, COLREG compliant lights and whistle, hi-vis colour scheme and wide/high mast, radar reflectors, watertight bulkhead with crash box.



#### **Designed for offshore survey**

Stability for optimal coverage and sensor performance



DriX – ballasted wave-piercing round-bilge **Planing V-hulls** roll. The steeper the deadrise, the more the vessel will roll in response to wave action.

**DriX is a ballasted round-bilge**. DriX remains upright even in high sea states with very little lateral roll.

**Planing V-hulls** pitch and 'slam'. This produces high bubble-sweepdown (aeration) around the hull which reduces acoustic performance.

**DriX is a wavepiercer design.** It pitches much less than a traditional V-hull. Instead, it cuts a smooth trajectory through the sea







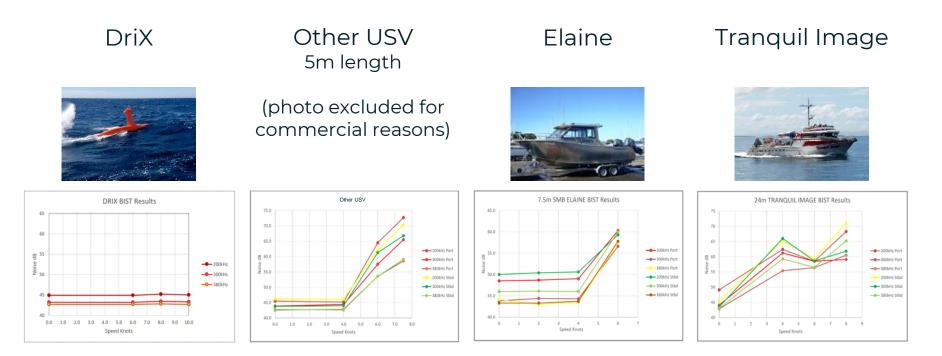
#### **Acoustic Performance**



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#### **Designed for offshore survey**

Silence for optimal sensor range and accuracy

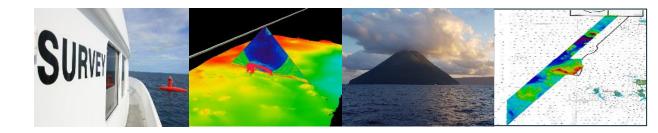


Low noise optimises acoustic sensor performance by increasing the SNR





#### Large offshore survey – Tonga 2018





Mothership with DriX as force multiplier

**Project location:** Kingdom of Tonga **Client:** Land Information New Zealand

**Specifications:** Improve navigational safety in wide corridors of over 200km in length.

Vessels (MV Silent Wings and DriX) to cover 694km<sup>2</sup> (over 7,500 planned linear km).



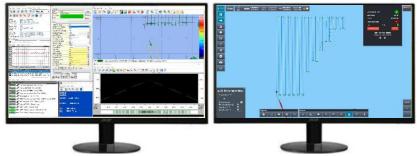
MV Silent Wings Fitted-out as Mothership and as survey ship



24/7 Operations

- DriX and MV Silent Wings operated within 3.5km of one-another
- DriX remained deployed for 24/7 operations
- Majority of data captured up to sea-state 4 with both vessels able to operate simultaneously in these conditions
- Single operator for DriX and MV Silent Wings survey systems







Lower cost per NM, improved environmental footprint

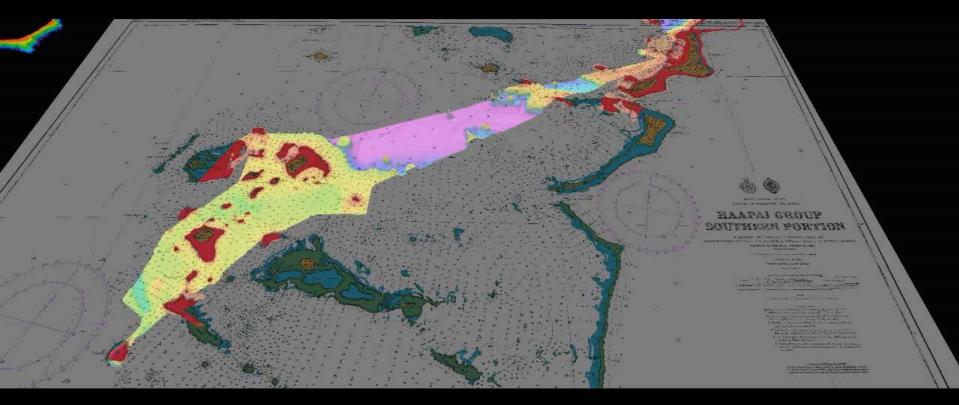
- Efficiencies realised by use of DriX
  - 33% project duration decrease
  - 20% overall cost decrease
  - 34% reduction in project carbon footprint



#### Tonga Project Metrics

| Parameters                        | Drix  | Mother<br>Ship |
|-----------------------------------|-------|----------------|
| Overall Line km                   | 7,450 |                |
| Line km                           | 2,360 | 5,090          |
| Effective survey time (hours)     | 166   | 358            |
| % of total line km                | 32    | 68             |
| Total use (days)                  | 19    | 37             |
| Average survey speed (knots)      | 7.6   | 7.6            |
| Average transit speed             | 10    | 10             |
| Autonomy (days)                   | 4-5   | 7              |
| Surveying fuel consumption (l/hr) | 2.4   | 66             |

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#### **DriX launch and recovery**

DAVIT

### Modifictions of the davit

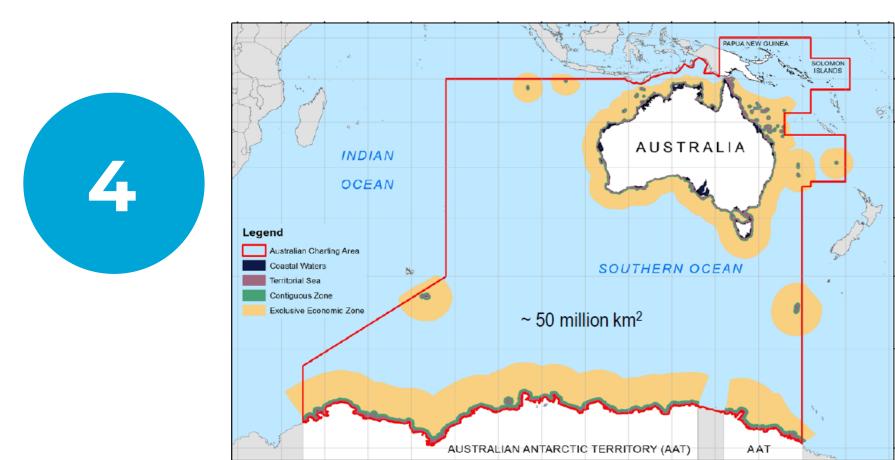
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#### NOAA Ship Thomas Jefferson



### **Enormous Challenge**



#### **Final thoughts:**

- Unmanned survey vessels have the potential to significantly increase the rate of effort of EEZ seabed survey
- USV have the potential to significantly reduce the cost of seabed survey
- The degree to which USV technology delivers cost effective seabed survey under the HIPP is now a function of the contracting model
- Industry can deliver survey at \$250/line mile if given sufficient budget to operate USV efficiently and on a large scale
- Assuming a budget of \$100M per annum, there exists the possibility to have Australia's EEZ fully surveyed within 50 years



# DriX



