# The use of highly economic, lighter class AUV's for shallow water infrastructure surveys

## Perth, 23rd October 2019





## AGENDA

Introduction to Blue Ocean Monitoring Background Equipment Proof of Concept Trials Survey Methods **Operational Results Future Ventures** 



#### MONITORING

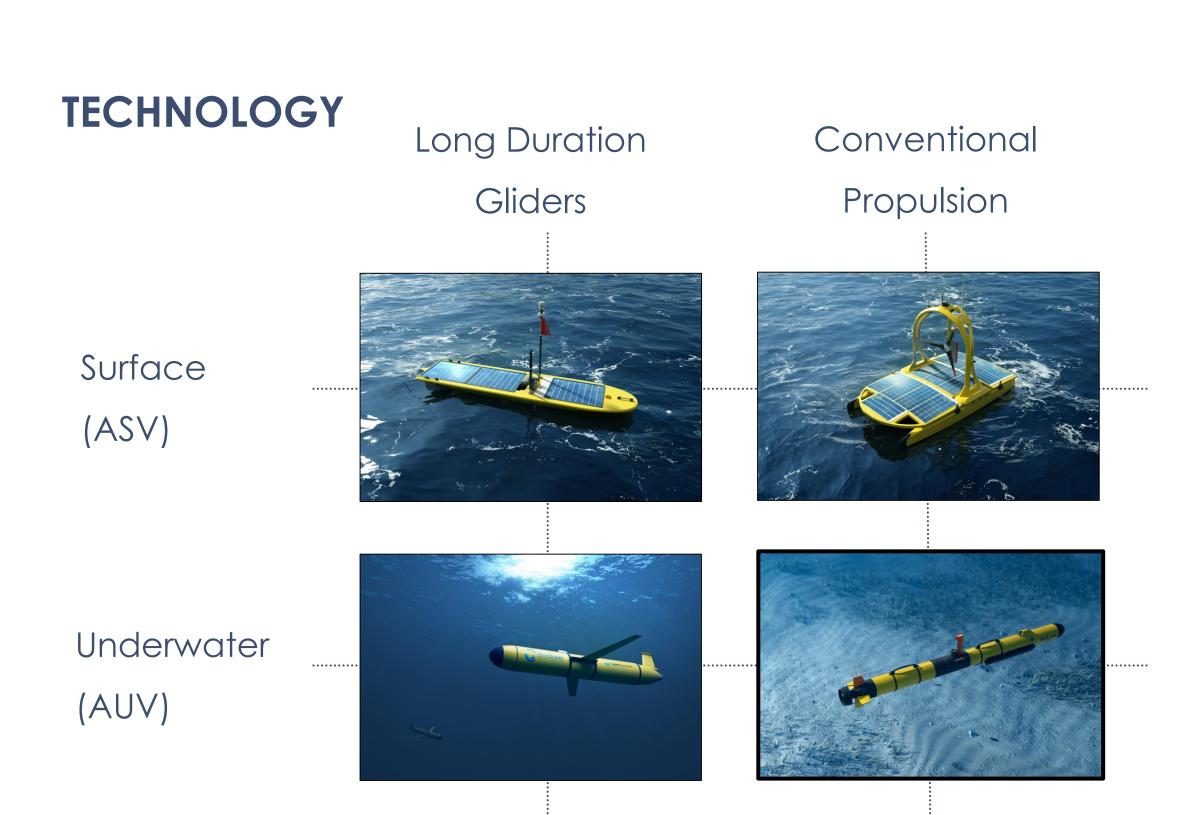
## **BLUE OCEAN MONITORING**

We are a global marine survey company, committed to providing highly innovative solutions to offshore industries.

- We Develop Autonomous Technology
  - Vehicle Modification and Refinement
  - Sensor Integration and Testing
  - Navigational and Control Systems

- We **Own/Operate** Autonomous Technology
  - Autonomous Underwater Vehicles (AUV)
  - Autonomous Surface Vehicles (ASV)



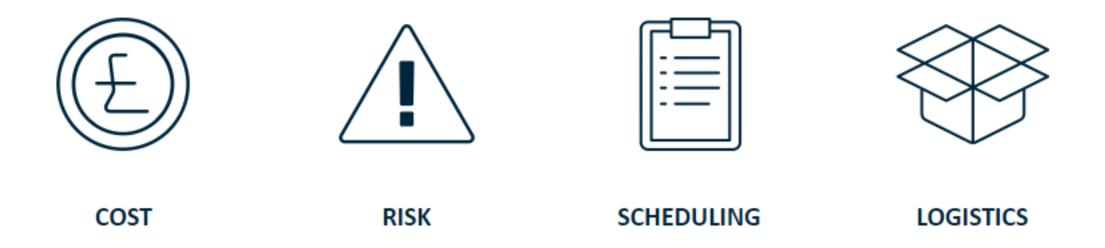


We adopt the latest generation of unmanned vehicles specifically designed to significantly lower project costs, reduce survey schedules and minimize human intervention.



## AUTONOMY

Autonomous vehicles are proven in to positively impact your offshore projects by reducing:

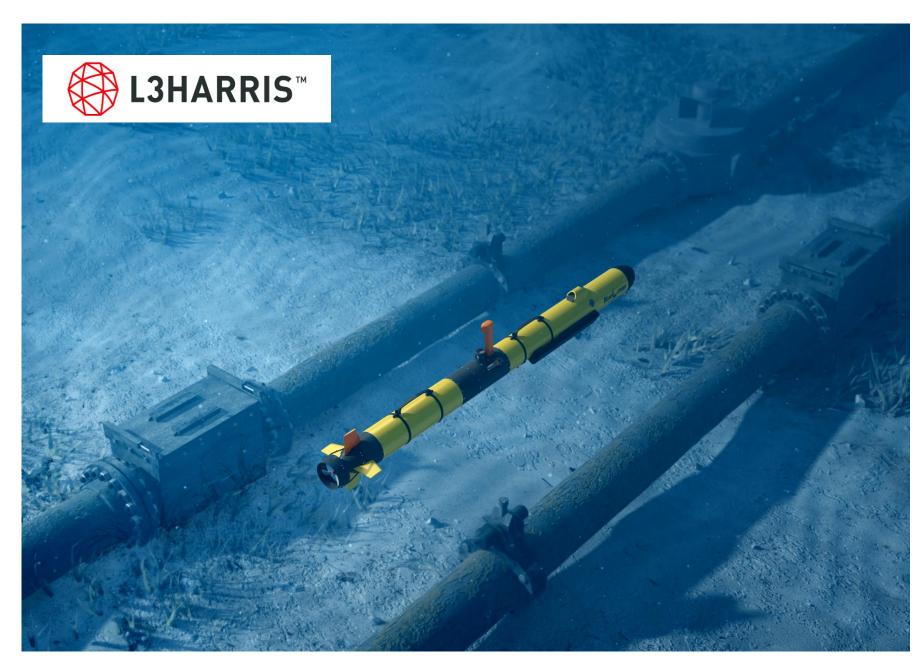


With minimal environmental impact and entirely reliant on onboard power supply, these technologies can significantly improve your specific data requirements in:





## **LIGHT CLASS AUV**



#### NAVIGATIONAL PAYLOAD

- Proven Technology
- Highly Economic
  - operations

#### **SENSOR PAYLOAD**

- Side Scan Sonar (SSS)

- Water Quality Sensors

Over 300 systems provided to Commercial, Academic and Defence Sectors

In comparison to conventional ROV or AUV

Minimal Vessel Requirement

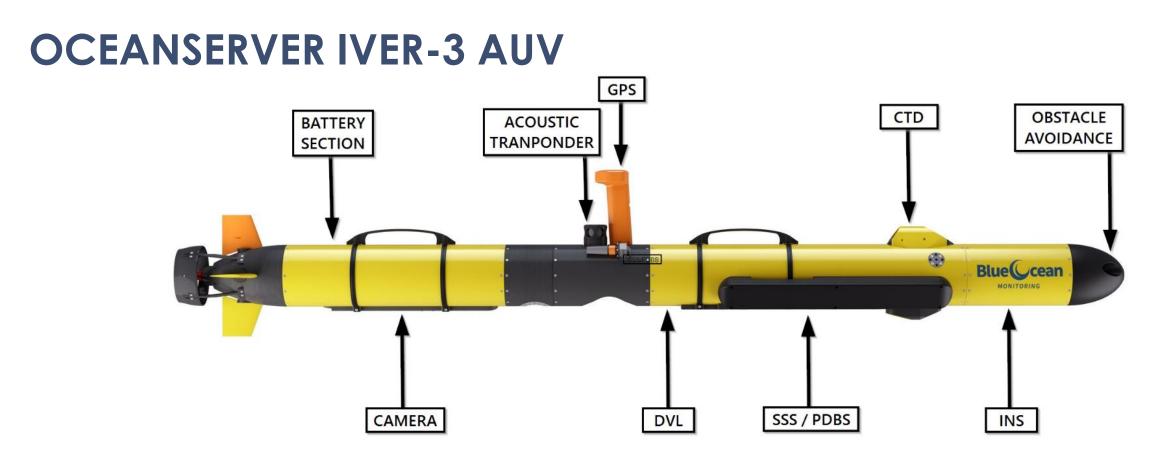
Small vessel operations with no LARS required

Interferometric Bathymetry (PDBS)

Digital Camera (Video and Still)

e.g. CTD, Turbidity, Fluorometry, DO, pH





Туре	Sensor	Manufacturer	Model
SSS	Side-Scan Sonar	EdgeTech	2205B (600/1600 kHz)
PDBS	Interferometric Sonar	Edgetech	2205B (600 kHz)
Camera	Digital Camera	Allied Vision	Mako G-234C
GPS	Global Positioning System	u-Blox	NEO-7P
СТ	Conductivity, Temperature Sensor	Neil Brown	NBOSI CT
INS	Inertial Navigation System	Ixblue	PHINS-C3
DVL	Doppler Velocity Logger	Teledyne	RDI Explorer
OAS	Object Avoid Sonar	Imaginex	UMS-852
Communication s	Acoustic Modem & Transducer	Blueprint Subsea	SeaTrac X010/X150

#### **IVER-3 DETAILS**

- Length: 1.8 2.1m
- Diameter: 0.15 m
- Weight: 30-35 kg
- Speed: 4 knots
- Duration: 4 8 hours
- Depth: 200 m



## **Oceanbotics SRV-8 ROV**

#### **SRV-8 DETAILS**

- Length: 0.50 m
- Width: 0.43 m
- Height: 0.33 m
- Weight in air: 18 kgs
- Tether Length: 250 m
- Speed: Up to 2 knots



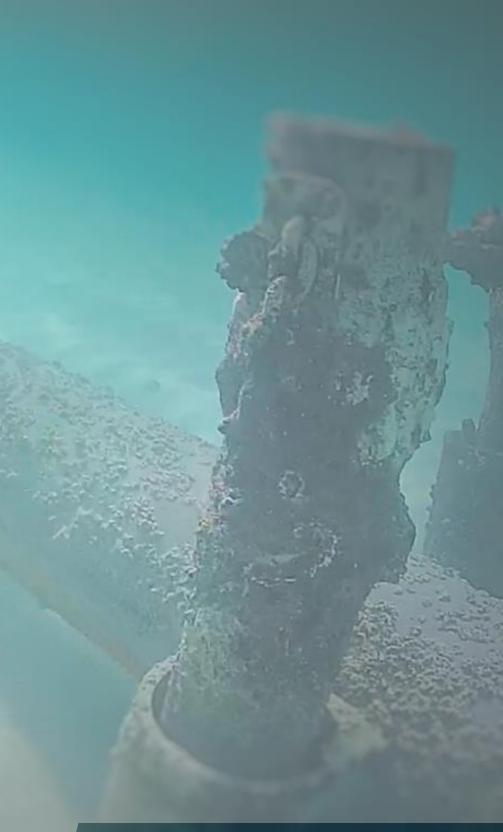
Sensor	Details		
Camera	Dual-Mode Low-Light Analog/HD		
Lights	Two 135° Beam Angle, 1500 Lumens Each		
Imaging Sonar	Blueprint Subsea Oculus M750d (750/1200kHz)		
Acoustic Communications	Blueprint Subsea Seatrac X010/X150		
Manipulator Arm	3-Jaw RJE Oceanbotics Grabber		



## **Proof of Concept**

Shallow Pipeline Inspection Surveys

LOCATION: Varanus Island, Western Australia WATER DEPTHS: 0 - 20 m DATES: September 2019





## PROOF OF CONCEPT – Varanus Island, Australia

### Scope of Work

AUV Survey Scope of Work

- North-East Pipelines (3 x 2.2 km)
- South-West Pipelines (3 x 1.5 km)
- Additional Points of Interest
- South-East Pipelines (3 x 1.5 km)

### **Primary Sensors**

- SSS Side Scan Sonar
- PDBS Interferometric Bathymetry
- Camera Digital Images
- CTD Conductivity, Temperature and Depth

### Objective

The ultimate objective is to assess free spanning, submergence, movement or deformation of pipeline and compare with results of previous surveys (vessel based, ROV and larger AUV conducted at this site).





## ORGANISATION

## **Project Requirements**

- On-Site Personnel: 2x AUV Operators
- Freight: 2x Pallets (which include 1x AUV & 1x ROV)
- Mobilization / Demobilization: 1-2 hours

RISK

Support Vessel: >10m



COST





SCHEDULING

!<u>=</u>

LOGISTICS





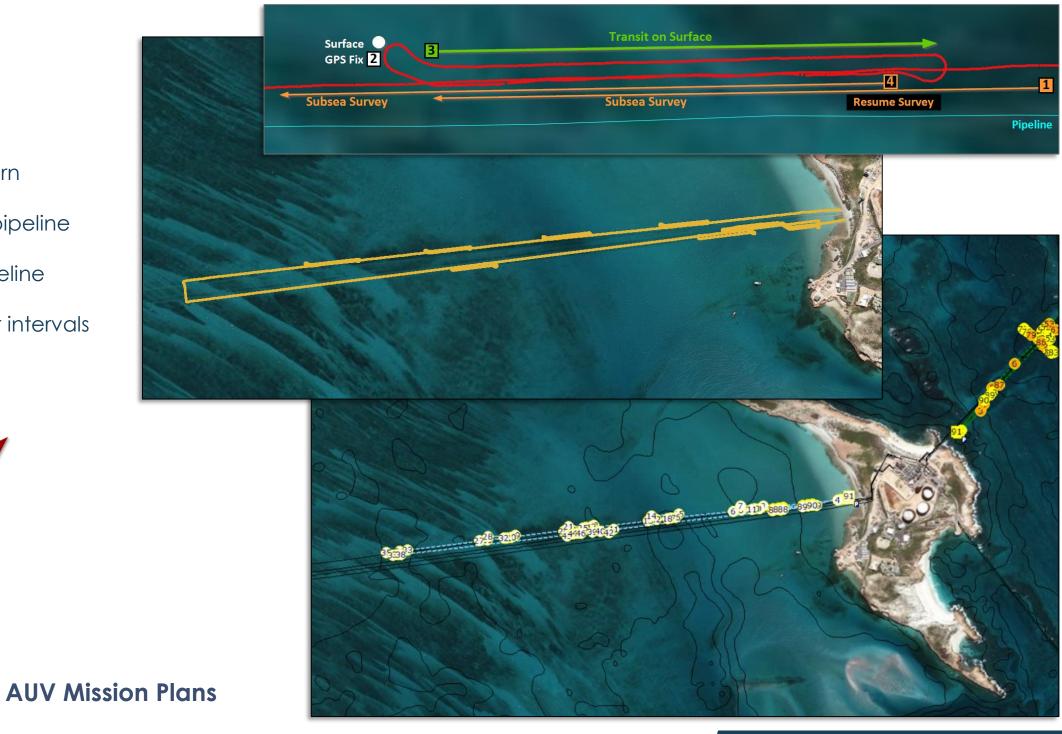


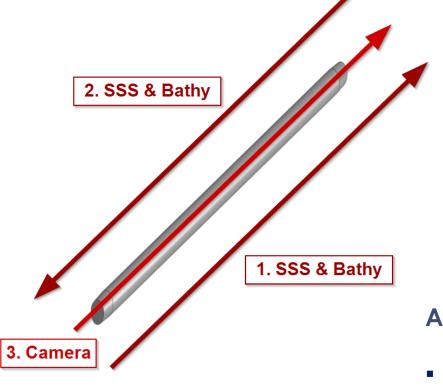


## **MISSION PLANNING**

#### Survey Methodology

- Run surveys from shore to depth & return
- SSS & Bathymetry Runlines 2x offset pipeline
- Camera Runlines 1x directly over pipeline
- Position correction surfacing at regular intervals





Created with OceanServer VectorMap Software



## **SURVEY SETTINGS**



#### Side Scan Sonar & Bathymetry Surveys

- Altitude Mode: 1m 3m / Depth Mode: 0.75m
- Speed: 2.5 knots
- Offset Pipeline: 8 15 metres

#### **AUV Camera Surveys**

- Altitude Mode: 2.3 metres
- Speed: 2.0 knots
- Mode: No Strobe





## **OPERATIONS**

### **AUV Launch & Recovery**

- All AUV launched from shore to depth
- Recoveries onshore and vessel safe, quick and easy





### **ROV Launch & Recovery**

ROV conducted visual inspections from both shore and vessel



## SIDE-SCAN SONAR DATA: North-East Pipelines



Pipeline Rock Dumping Site





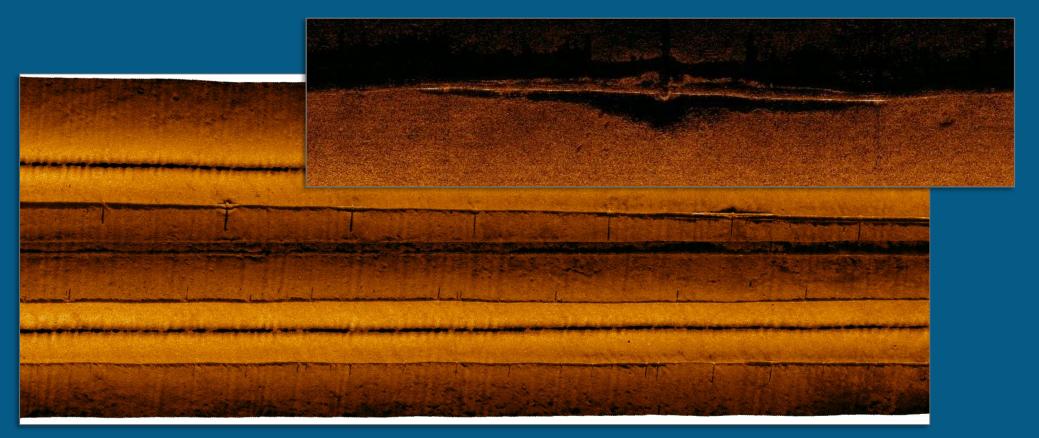
## **SIDE-SCAN SONAR DATA: South-West Pipelines**



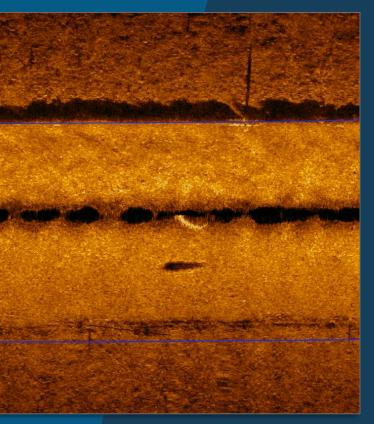
#### Seabed Characterisation



#### Infrastructure Visualisation



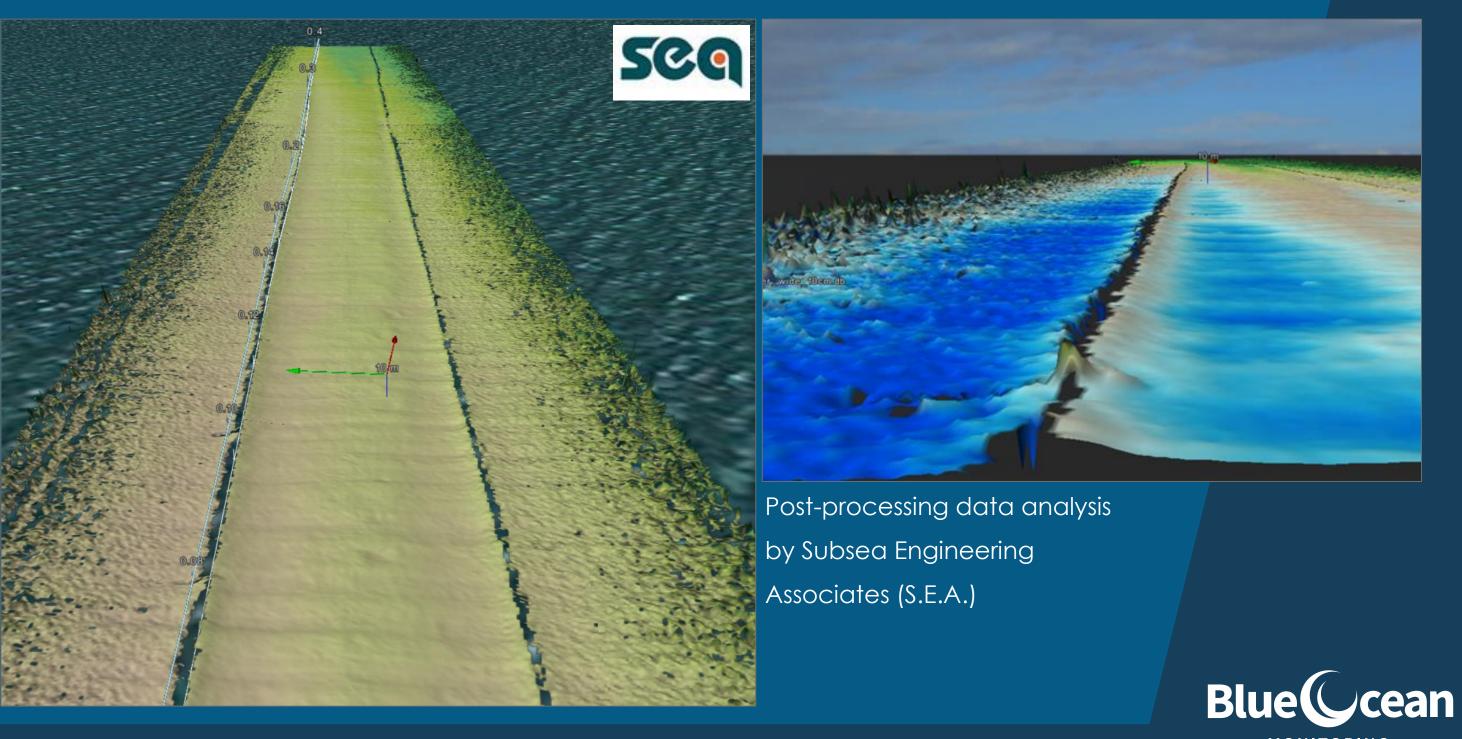
Pipeline Freespan Identification



#### **Environmental Identification**



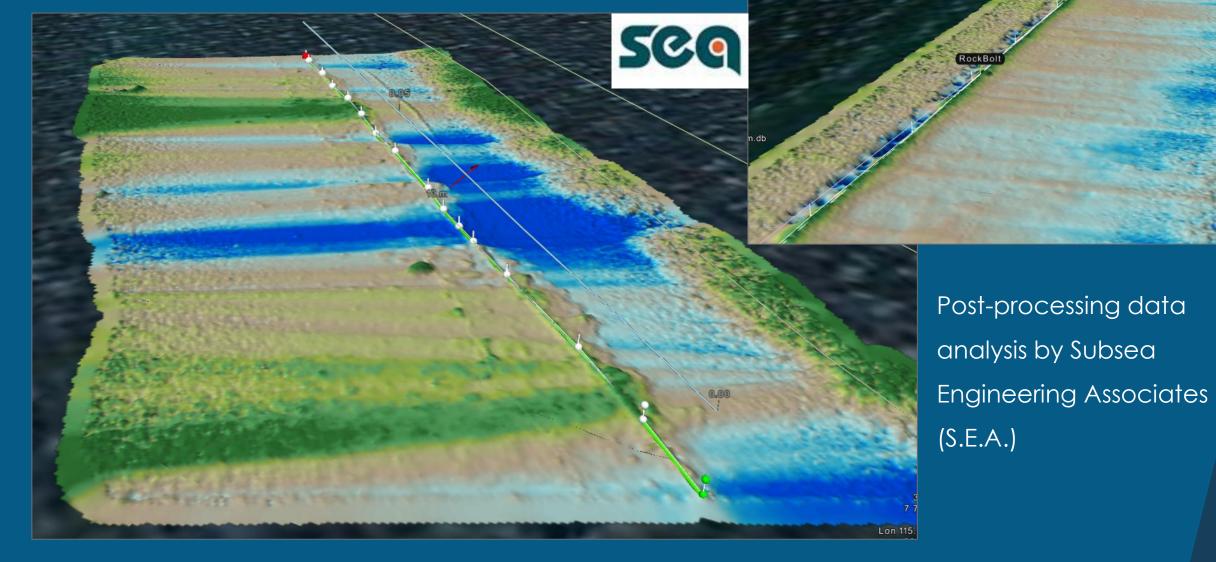
## **BATHYMETRY DATA: South-West Pipelines**



MONITORING

**BATHYMETRY DATA:** 

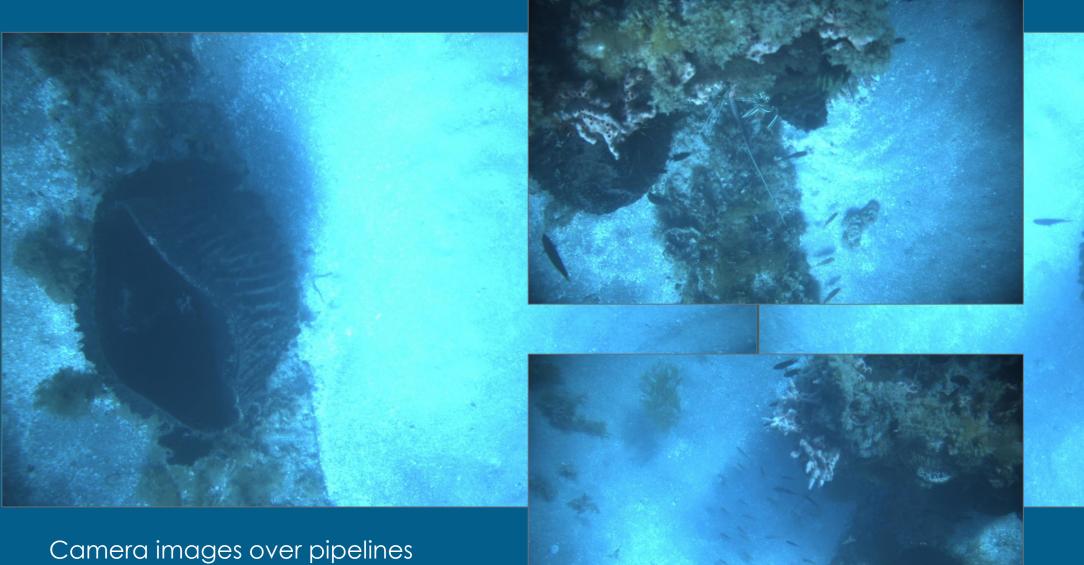
## South-West Pipelines







## **AUV CAMERA DATA: South-West Pipelines**



Camera images over pipelines depicting marine growth & environmental ecosystems



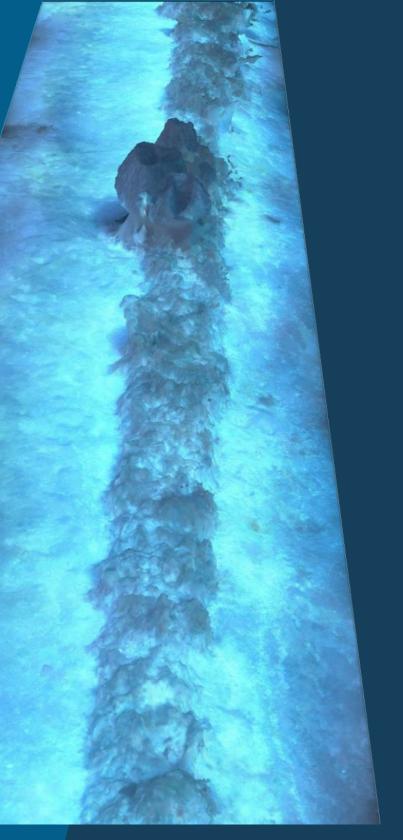


#### MONITORING

AUV CAMERA Data:

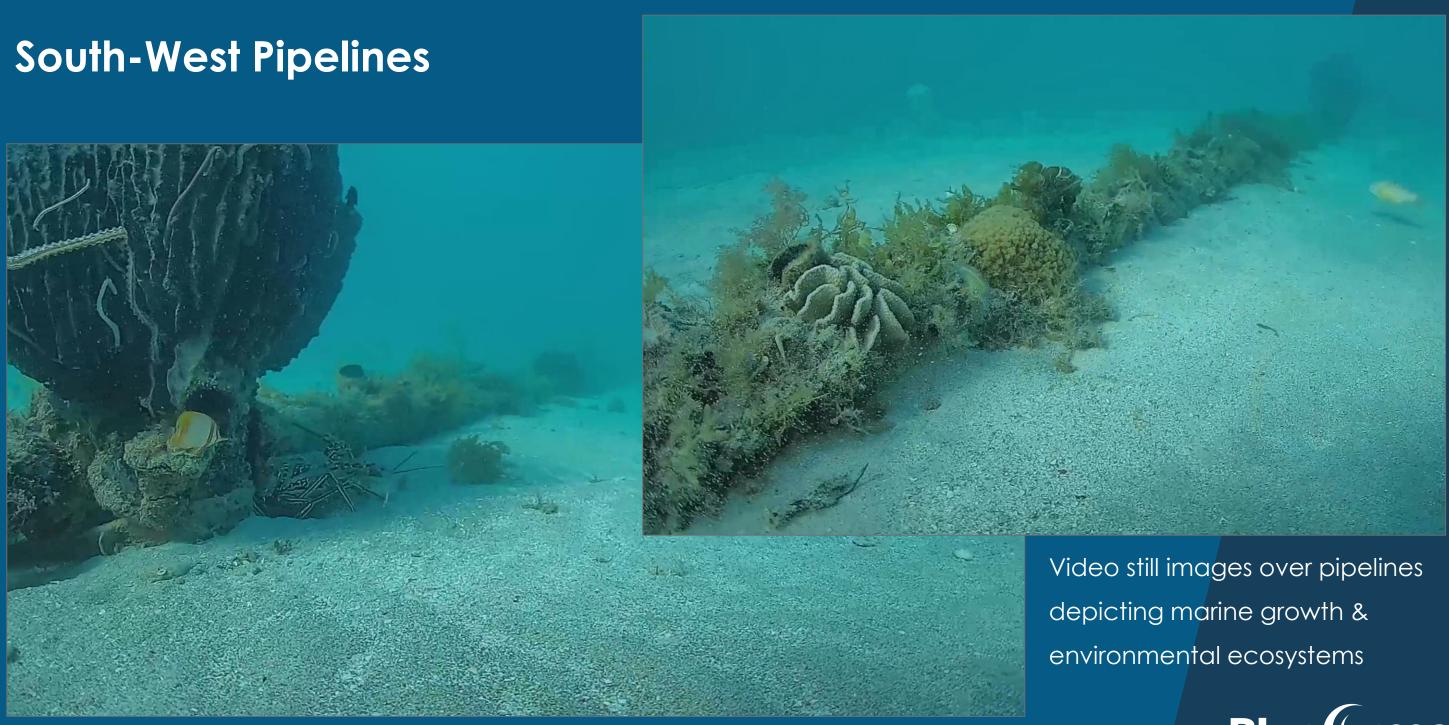
South-West Pipelines

Post-processed camera mosaic data over pipeline.





## **ROV VIDEO DATA:**





## **ROV VIDEO DATA:**

## South-West Pipelines







## **Project Outcomes**



#### **Lessons Learnt**

- ✓ Platform Stability: AUV handles well in shallow coastal conditions
- ✓ Launch & Recovery: from vessel or shore efficient and safe.
- 3. ✓ Accuracy: Correctly navigate AUV to survey intended pipeline structure.
- ✓ Quality: Acquire consistent and accurate SSS and Bathy data at required resolution over length of pipeline.
- 5. ✓ Accessibility: System flexibility accommodated operational variations
- 6. ✓ Camera: Test newly integrated digital camera along pipeline structure
- ✓ Speed: Fast data download (~50GB in 8 minutes)



# **Preliminary Data Analysis**

### **Data Quality**

- SSS Excellent. High Quality Data.
- PDBS Bathy Good.
  - Affected by currents and shallow depths
- Camera Suitable images
  - Over exposure imagery
- Positioning good

#### **Recommendations**

 Further tests to determine the optimal survey methodology for data acquisition in a variety of environments.



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## **AUV OUTLOOK FUTURE**

- 1. Procure OceanServer Iver-3
- ✓ Ordered, received early September 2019
- 2. Conduct <u>Pipeline Inspection</u> Proof of Concept
- ✓ Project completed at Varanus Island Facility, Western Australia in September 2019 (7 days)
- 4. Conduct Series of Commercial Water Quality and Bathymetry Surveys
- Project secured with major client in Southern Indonesia in November 2019 (30 days)
- 5. Conduct Pipeline Inspection Proof of Concept
- Project secured in Malaysia in December 2019 (5 days)
- 6. Procure Second OceanServer Iver-3 AUV
- Planned in January 2020





## **RESEARCH AND DEVELOPMENT 2019/2020**

#### **Non-Contact Cathodic Protection**



- Successfully trialed on larger AUV and ROV platforms
- Iver-3 compatible prototype expected Q4 2019
- Blue Ocean Monitoring to trial system in Q2 2020 in Australia

**3D Laser Scanning** 



- Successfully
- trialed on larger AUV and ROV platforms
- Iver-3 compatible prototype expected Q3 2019
- Blue Ocean Monitoring to trial system in Q1 2020 in Australia









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# **BLUE OCEAN MONITORING**

www.blueoceanmonitoring.com

# QUESTIONS?

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